

Design and Modeling of Karabuk University Microgrid

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ABSTRACT

Last decades with rapidly penetration of distributed energy resources to the power system, the interest on Microgrid is growing. Microgrid as a key component of the Smart Grid can be used in rural areas, especially in remote inaccessible areas or with main grid. Objective of this paper is to design and modelling of Microgrid for Karabuk University (KBU) campus for Microgrid disconnected and connected to main grid operation modes. In this paper are considered simulation models of islanded and grid-connected operation modes of Karabuk University Microgrid on MATLAB/Simulink.

Keywords: Microgrid, Distributed Energy Resources, Karabuk university, MATLAB.

I. INTRODUCTION

Nowadays it is clear that the challenges facing the energy sector are becoming acuter. The problems such as environmental protection, energy security and economic development are interrelated and global of the modern era. In recent years, the rapid development of power electronic system and innovations in small-scale distributed generation (DG), also implementation of new information and communication technology in the power systems led to the concept of smart grid (SG).

Microgrid (MG) as a key component of the Smart Grid can be used in rural areas, especially in remote inaccessible areas or with main grid. MG is intended to improve energy efficiency, a reliability of power system and decrease carbon dioxide emissions. Fluctuation and intermittence resulted from unstable micro-sources and nonlinear loads will execute considerable impacts on normal operation of the MG. The term "Microgrid" refers to the concept of MV/LV distribution network voltage associated with a small number of distributed energy resources (DERs), such as photovoltaic, wind power, hydro, internal combustion engine, and microturbine together with loads [1]. In MG distribution network becomes active with integration of DER, demand side integration and energy storage technologies [2]. In EU research projects MG described as "Microgrids comprise LV

distribution systems with distributed energy resources (DER) (microturbines, fuel cells, PV, etc.) together with storage devices (flywheels, energy capacitors and batteries) and flexible loads"[3,4]. The works [5,6,11] conducted by researchers present technical, economic and environmental benefits associated with MGs.

The high penetration of distributed generator (DG)s increases the intricacy of control, protection, and communication of distribution systems. Therefore, an important problem is how to integrate various DGs into the existing distribution networks of power system by limiting their potentially negative side-effects on distribution network operation and control. MG can be operated [7,8]:

- 1) in stand-alone or islanded mode, if MG operates autonomously;
- 2) in grid-connected mode, if MG connected to the main grid.

In stand-alone mode, microsources provide loads with necessary power energy and MG never connects to the main grid.

In grid-connected mode, MG remains connected to the main grid either totally or partially and extra power generated in MG can be exchanged with the main grid providing auxiliary services.

MG consists of a group of radial feeders (A, B and C), which could be part of a distribution system architecture and a collection of loads. The radial system is connected to the distribution system by a point of common coupling (PCC) via a static switch. The Point of Common Coupling (PCC) is on the primary side of the transformer and separates main grid from MG. Each feeder has a circuit breaker and microsource controller [6]. Local critical loads connected to the local generation resources while non-critical loads do not have any local generation. The static switch is capable to disconnect MG from main grid when fault occurs or for maintenance purposes.

II. MODELING OF MICROGRID SYSTEM

Modeling of MG is a main step to provide a suitable control. The structure of Karabuk University (KBU) microgrid is represented in Figure 1. The

single line diagram of MG is illustrated in Figure 2. Karabuk University substation with TR 1A and distributed energy resources (PV-panel, diesel generator) are chosen for a case study of MG implementation on Simulink/MATLAB. Research

analysis show that potential of wind energy in Karabuk region is low with 2.4 m/s annual average wind speed and 21.3 W/m² annual average wind density [9,10]. Therefore, modeling of MG with wind turbine for Karabuk university is not proper.

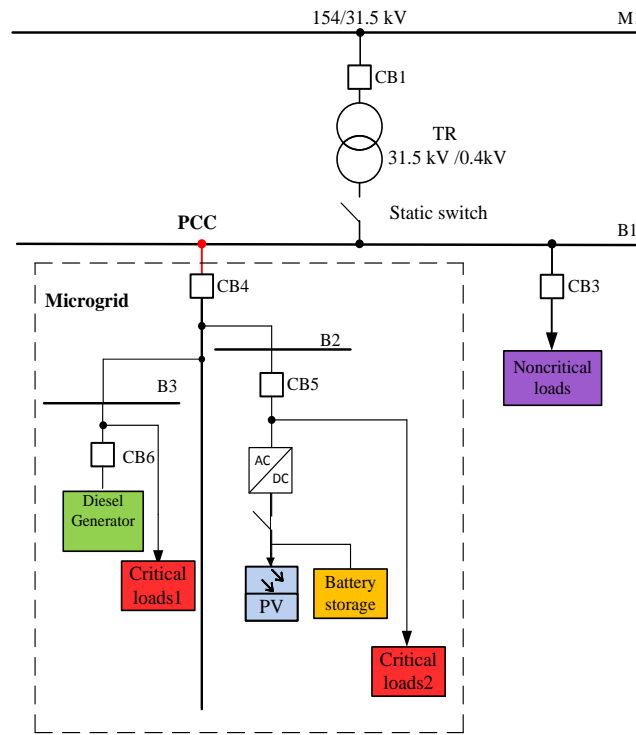


Figure 1: Structure of Karabuk university Microgrid.

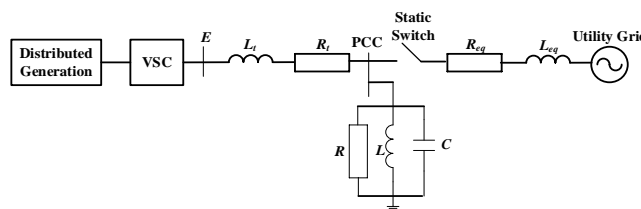


Figure 2: Single line diagram of KBU MG.

2.1. Modeling of Photovoltaic module

PV system configuration consists of solar photovoltaic cells, referred to as PV modules, a boost converter and an inverter. Equivalent electric circuit of PV cell (Figure 3) is used for modeling PV system. The output of PV systems is directly affected by solar irradiance and temperature. The output of PV module can be written as follows

$$I = I_{pv} - I_D - I_{sh} \quad (1)$$

where: I - output current; I_{pv} - photo generated current; I_{sh} - shunt current. I_D - diode current. Using the Shockley diode equation diode current can be written:

$$I_D = I_0 \left(e^{\frac{qV_D}{kT}} - 1 \right) \quad (2)$$

where: I_0 - reverse saturated current; k - Boltzmann constant ($1.381 \times 10^{-23} \frac{J}{K}$); q - electron charge ($1.60217662 \times 10^{-19} C$); T - absolute temperature.

The current through shunt resistor is equals

$$I_{sh} = \frac{V_D}{R_{sh}} \quad (3)$$

The voltage across the diode and the shunt resistor as follows:

$$V_D = IR_s + V \quad (4)$$

where: V is output voltage; R_s is series resistor.

Characteristic equation of PV cell is expressed by substituting (2) - (4) into (1)

$$I = I_{pv} - I_0 \left(e^{\frac{qV_D}{kT}} - 1 \right) - \left(\frac{IR_s + V}{R_{sh}} \right) \quad (5)$$

The dynamics all DGs are represented in [11]. The transfer function of PV system while network is neglected is a first-order lag as

$$G(s) = K_{PV} / (1 + sT_{PV}) \quad (6)$$

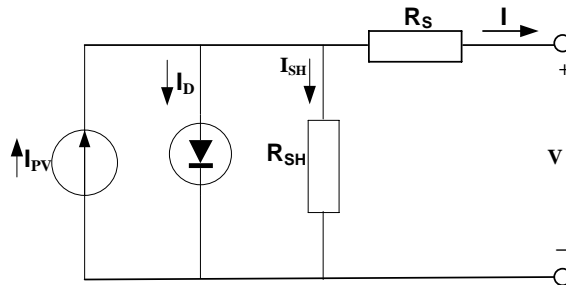


Figure 3:Equivalent electric circuit of PV cell.

2.2. Modeling of battery energy storage

Lead-acid battery is considered for the battery storage modeling. This type of battery energy storage system (BESS) is widely and effectively used element for storage unit in PV system. In Figure 4 is shown the equivalent electric circuit of battery. It consists of a controlled voltage source in series with

an internal resistance R_i . The circuit equation model is expressed in the following view [11]:

$$V_{bat} = E_b + R_i I_{bat} \quad (7)$$

$$E_b = f(\text{SOC}) \text{ and } R_i = f(I_{bat}, \text{SOC}, T) \quad (8)$$

where: V_{bat} - voltage of battery; I_{bat} - current of battery, E_b - electromotive force as a function of the battery state of charge (SOC), and R_i - the internal resistance of an element.

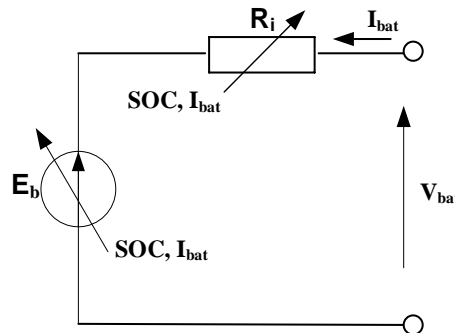


Figure 4:Equivalent electric circuit of battery model.

In [11] proposed the model for discharging and charging of lead-acid battery.

The discharge model:

$$V_{bat} = E_o - R_i - K((Q/Q - it)(it + i^*) + \text{Exp}(t)) \quad (9)$$

The charge model:

$$V_{bat} = E_o - R_i - K(((Q/Q - 0.1Q)i^*) - K((Q/Q - it)it) + \text{Exp}(t)) \quad (10)$$

where: E_o - battery constant voltage; i^* - filtered current; Q - battery capacity (Ah); it - actual battery charge; K - polarization constant (V/(Ah)) or polarization resistance (Ω). The simplified transfer function of battery energy storage system (BESS) can be given as follows:

$$G(s) = K_{BESS} / (1 + sT_{BESS}) \quad (11)$$

2.3. Modeling of boost converter with MPPT

The maximum output power of PV module varies and to obtain the maximum power from PV

system maximum power point tracking (MPPT) is used. There are many different methods described in [12,13,14] to maximizing the power from PV system. In this work is used classical perturbation and observation method (P&O) by the reason it is much simpler and needs fewer measured variables. The boost converter provides maximum efficiency operation of PV system by extracting maximum achievable power from PV system. The P&O method is based on to create a perturbation by decreasing or increasing the duty cycle of boost converter and then observing the direction of change of PV output. The algorithm of P&O method is illustrated in Figure 5. Firstly, PV voltage and current must be initially measured. Then the change in the voltage (ΔV) and the change in the power (ΔP) must then be calculated. The PV voltage must be perturbed by a constant value. If the perturbation in the voltage causes the power to increase, the next perturbation must be kept in the

same direction; otherwise, the next perturbation must be reversed [15].

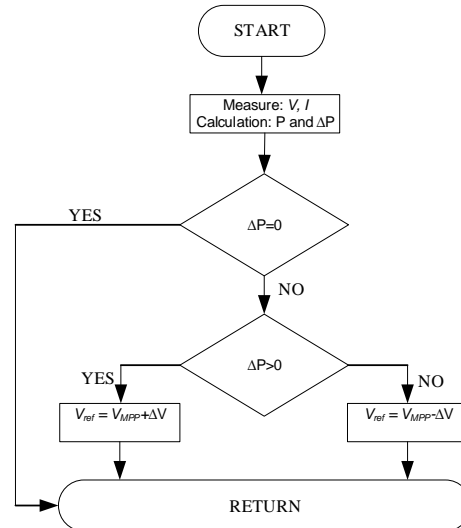


Figure 5: Flow chart of P&O method.

2.4. Modeling of voltage source inverter

In MGs the three-phase voltage source inverter (VSI) is used to connect DC bus to AC grid [16,17]. The purpose of the inverter is to invert DC into AC voltage in real-time. The equivalent model of three-phase inverter is shown in Figure 6[18]. The

circuit consists of voltage source v_{in} in series and output impedance $Z_0 \angle \theta$, where δ is power angle – difference between $v_{rand} v_0$, E is the amplitude of the voltage source and δ .

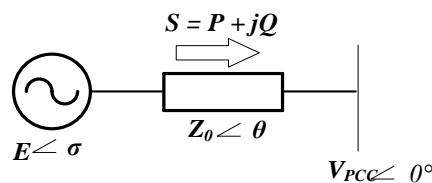


Figure 6: The equivalent model of three-phase inverter.

In several papers [16-20] the block diagram of VSI control loop was developed in detail for MG systems. One of this block diagram of VSI control loop is illustrated in Figure 7.

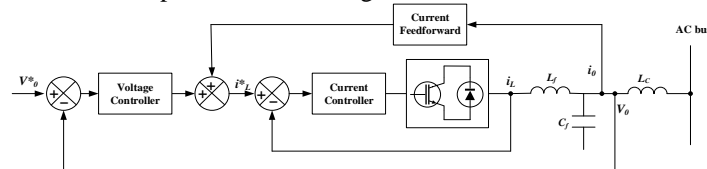


Figure 7: Block diagram of VSI control loops.

III. SIMULATION STUDY

Simulation model of KBU MG is implemented on three-phase, 3-bus, 0.4 kV for islanded and grid-connected operation modes on MATLAB/Simulink. Simulation model is developed

according to the structure scheme of KBU MG in Figure 1 (Figure 8). Details of DER and loads which are used for MG simulation are given in Table 1.

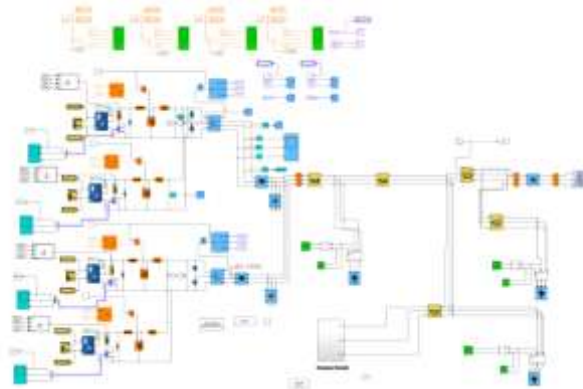


Figure 8: Simulation model of KBU Microgrid on MATLAB/Simulink.

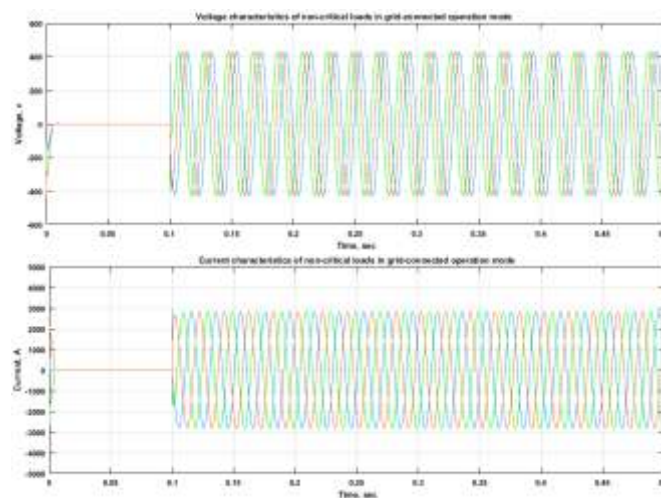
DER	Units number	Min. Power, kW	Max. Power, kW
PV	4	21	24
Diesel Generator	1	375	400
Loads			
Critical loads1	20	216.4	226.57
Critical loads2	3	14.18	21
Non-critical loads	35	520	550
Total Loads		750.58	797.57

Table 1: Details of DER and Loads of KBU MG.

3.1. Grid-connected operation mode

In grid connected mode MG becomes as load that control by main grid. Similar to power system in this mode the distributed generations are controlled to generate active and reactive power. PV loads, diesel generator loads and noncritical loads dynamical performances are illustrated in Figures 11, 12 and 13 respectively. Simulation result of three-phase voltage

at PCC shows while the interconnection from islanded to grid-connected mode there is delay time of 0.1 sec (Figure 14). The results demonstrate that control of DERs and coordination of loads sharing is an effective way to provide the reliability of MGs. Therefore, the purpose of the DG is to control the output real power and reactive power.



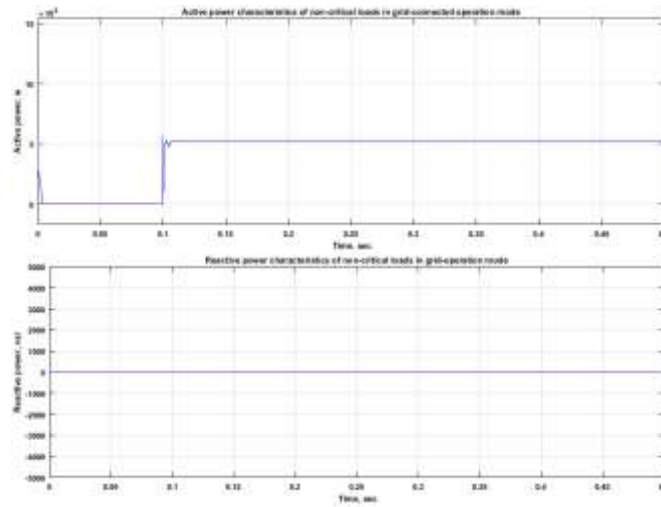


Figure 12: Dynamical performances of non-critical loads in grid-connected operation mode.

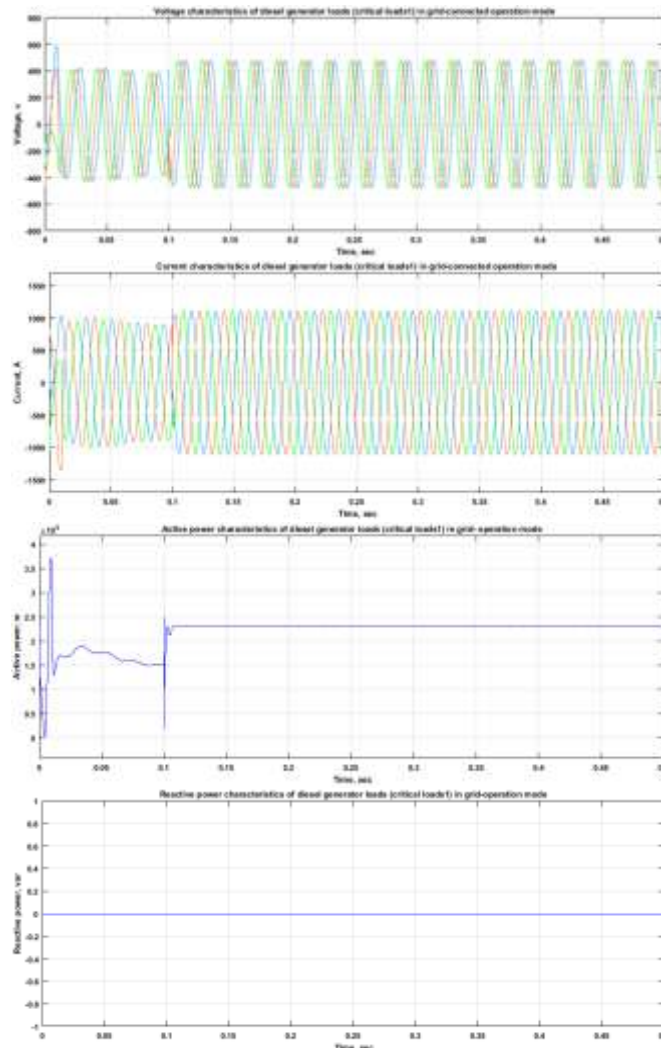


Figure 12: Dynamical performances of diesel generator loads (critical loads1) in grid-connected operation mode.

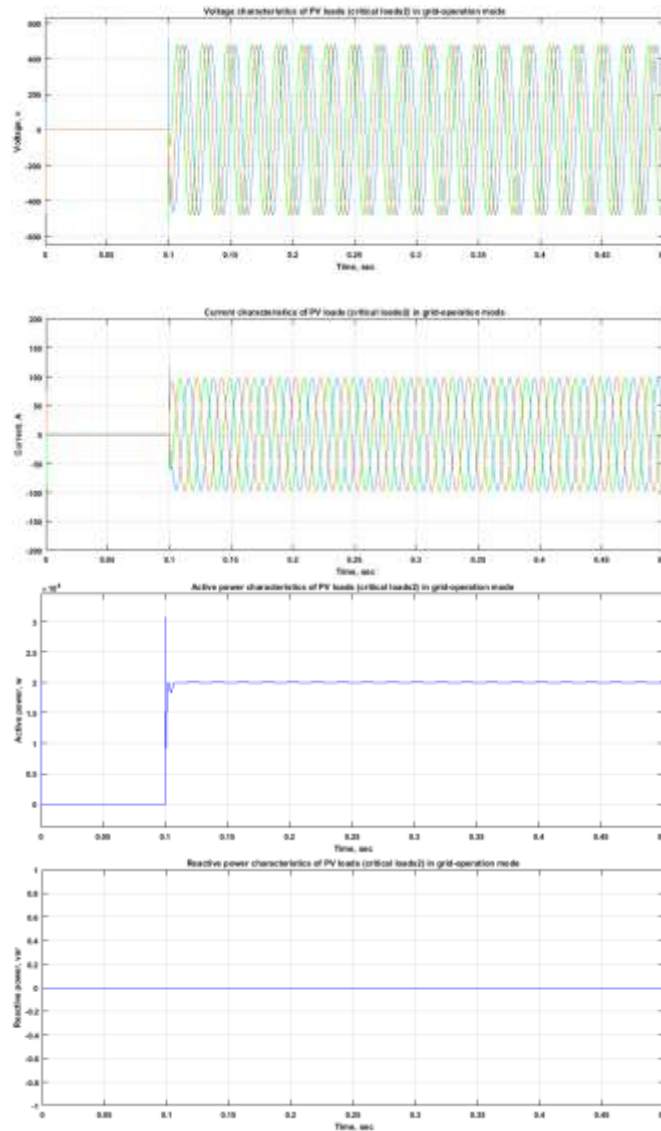
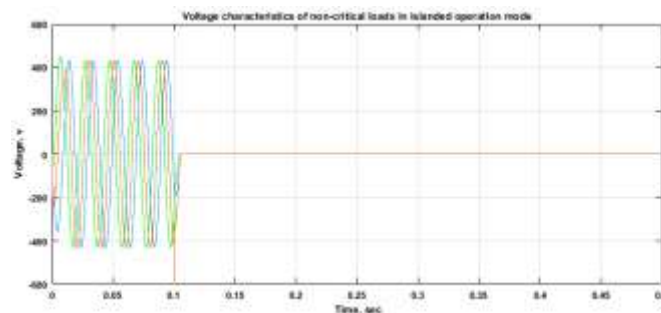


Figure 11: Dynamical performances of PV loads (critical loads2) in grid-connected operation mode.

3.1. Isolated operation mode

If in the main grid occurs faults or power outages, MG is disconnected from main grid and non-critical loads cut-off from power system. The dynamic performances of PV loads in isolated operation mode

are shown in Figures 9. The characteristics shows that at 0.5 sec. PV system reaches steady operation. Another critical load – diesel generator loads dynamic characteristics are shown in Figure 10.



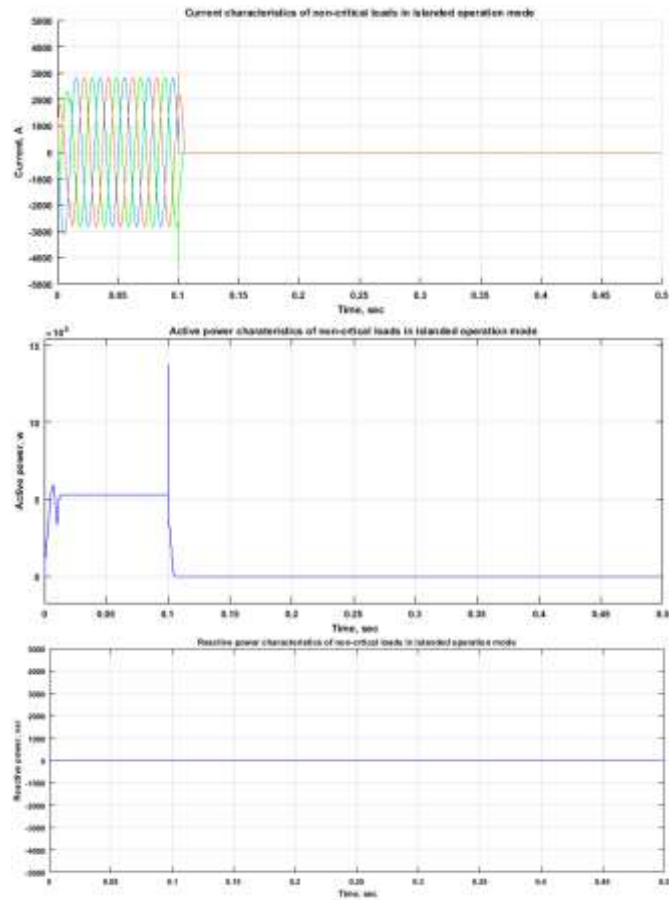
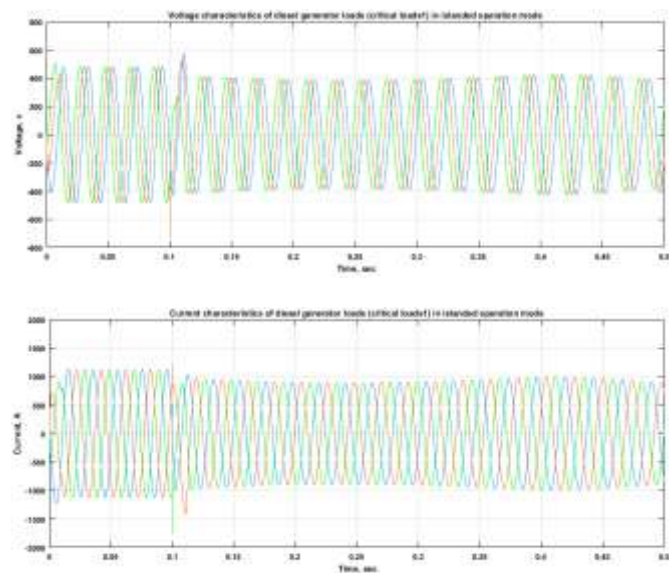


Figure 9: Dynamical performances of non-critical loads in islanded operation mode.



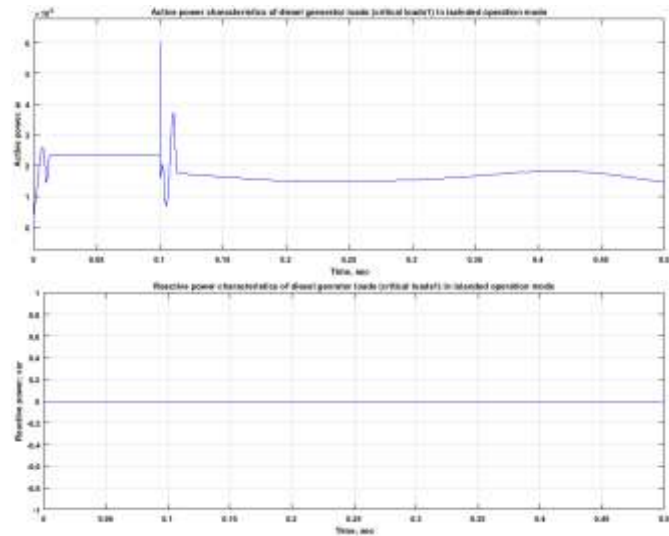
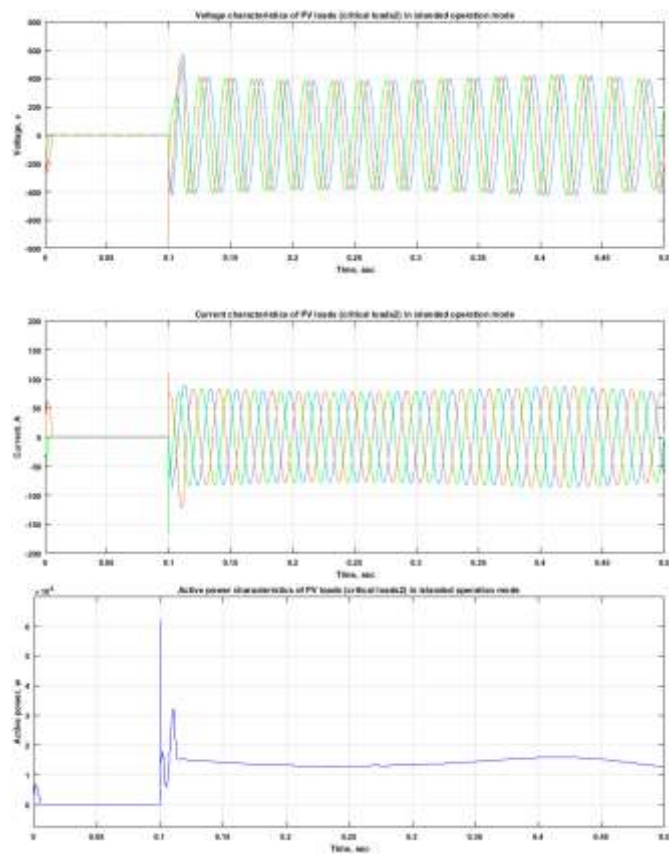


Figure 11: Dynamical performances of diesel generator loads (critical loads1) in islanded operation mode.



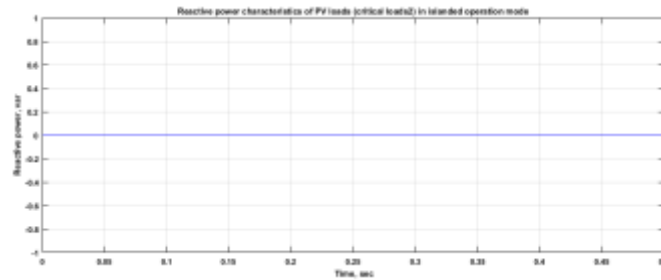


Figure 11: Dynamical performances of PV loads (critical loads2) in islanded operation mode.

IV. CONCLUSION

Microgrid is consists of DERs, energy storage units and loads in LV distribution network. The integration of DERs into distribution network requires to provide the stability and reliability operation of MG by the reason of fluctuation and intermittence of micro-sources and nonlinear loads.

The mathematical and simulation models of KBU MG are developed in this paper. The case studies of KBU MG simulation are carried out on three-phase, 3-bus, 0.4 kV for disconnected and grid-connected operation modes. The simulation results of KBU MG operation modes show that control of distributed energy resources and coordination of loads sharing is an effective way to provide the reliability of MG. Results and conclusions that obtained in this work will apply to integrate distributed generation in KBU campus.

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